#### Elsevier Editorial System(tm) for International Journal of Plasticity Manuscript Draft

Manuscript Number:

Title: The Effect of Dynamic Plasticity on the Crack Propagation in Thin Plates Subjected to Impact Loading

Article Type: Research Paper

Keywords: Crack Propagation, Plastic Zone Size, Elastoplastic Stress Field, Elastoplastic Strain Field, Experimental Plastic Strain, Impact Loading, Elastoplastic Stress Intensity Factors

Corresponding Author: Mr. Muthenna Abdul-Hussein Ali, -

Corresponding Author's Institution: Baghdad University

First Author: Muthenna A Ali, Researcher

Order of Authors: Muthenna A Ali, Researcher; Fathy A Al-Shamma, Assistant Professor

Abstract: In the present study an investigation upon simply-supported thin plates having surface cracks within their structure is to be accomplished, and the applied impact load to these thin plates tends to induce infinite stresses and strains at the crack tip of the existing cracks. Extensions of these cracks may be evolved from the crack tip, and the cracks may propagate in a specified path with certain velocities. At the same instant, yielded zones are emanated around the crack tip due to occurrence of the impact load. Two methods of computation are utilized here; the first one is the analytical method which is derived from the classical plate theory, whose concepts are illustrating the required expressions of plane stress conditions for thin plates, taking into consideration the effects of impact loading in conjunction with the elastoplastic fracture mechanics and dynamic crack growth concepts. The second technique is the experimental analysis using the grid method (remeshing technique); so as to measure the permanent strains induced within the grid points within the plates. Finally, a total solution leads to the arrival at the analytical and experimental results concerning the crack-development speed, plastic-zone size, and the crack-tip-nearby elastoplastic stress and strain fields.

# The Effect of Dynamic Plasticity on the Crack Propagation in Thin Plates Subjected to Impact Loading

Muthenna Abdul-Hussein Ali

Mechanical Engineering Department – Baghdad University – Al-Jadiriyah – Baghdad – Iraq

+9647901831234

Muthenna\_rockstar@yahoo.com

### Fathy Abdul-Sahib Al-Shamma

Mechanical Engineering Department – Baghdad University – Al- Jadiriyah – Baghdad – Iraq

+9647810846720

Fathi-Alshamma@yahoo.com

# <u>Highlights</u>

- Utilizations of the plate-theory considerations and the impact-load nature in conjunction with the elastoplastic-fracture-mechanics concepts are to be elaborated for the present mathematical model.
- An implementation of a finite-dimensions grid upon the elastoplastically-deformed cracked plates is achieved to measure the permanently-induced displacements.
- A remarkable contrast between the crack-growth-speed values and the around-crack-tip plastic-zone extensions is to be investigated.
- We process the crack-tip-nearby stress and strain fields' behavior for the linear elasticideally plastic-based cracked plates.

# Nomenclature:

<sup>2</sup> Symbol	Description	Units
3 4 A	Contact Area between the Plate	<i>m</i> <sup>2</sup>
5	Surface and the Striking Bullet	
$\frac{1}{2}a$	Plate Width	ст
8 9 a <sub>c</sub>	The Critical Crack Length	mm
$\frac{0}{1 a_{cr}}$	Characteristic Crack Length	mm
$\frac{2}{2}$	Speed of the Crack Propagation	$m_{/s}$
$\frac{3}{4}$ $a_{0}$	The Existing Crack Length within	, s mm
5 6	the Thin Plates	
<sup>7</sup> ∘ AR	Plate Aspect Ratio	_
9 h	Length of the Thin Plate	ст
$\frac{0}{1}$	Plastic Zone Size	mm
$\frac{2}{2}$	Distance between the Pistol and	m
3 u 4	the Thin Plate Where the Velocity	m
5 6	of Bullet Becomes Zero	
7 9 E	Modulus of Electicity	Mag
8 E 9		мра
$\frac{1}{1}$ F(t)	Time-Dependent Impacting Force	N
$\frac{1}{2}$ G	The Energy Release Rate	N
${}^{3}_{4}g$	Gravitational Acceleration of	$m_{/_{S^2}}$
5	Earth	
7 h	The Thickness of the Plate	mm
${}_{9}^{8}$ K <sub>I</sub>	The Elastic Stress Intensity Factor	Mpa. $\sqrt{m}$
${}^{0}_{1}$ K <sub>I,ep</sub>	The Elastoplastic Stress Intensity	Mpa. $\sqrt{m}$
2	Factor	
$\frac{3}{4}$ $M_x$	X-Axis Bending Moment	N.m
${}^{5}_{6}M_{y}$	Y-Axis Bending Moment	N.m
$\frac{7}{2}m_o$	Mass of the Copper-Covered	kg
8 9	Bullets	
$\frac{0}{1} P_{o}$	Contact Pressure between the	Мра
2	Thin Plate Surface and the	-
5 4	Impacting Bullets	
5 6 R	The Crack Resistance	N
$\frac{7}{r}$	The Variable Radial Position	mm
8 9		
0		

t	The Time Duration of Contact	μs
	between the Thin Plate and the	
	Striking Bullet	
$\begin{bmatrix} u_x \\ \cdots \end{bmatrix}$	Elastoplastic Displacement Field	μm
$[u_y]_{ep}$	near the Crack Tip	
$v_1$	Muzzle Velocity of the Bullets	$m_{/s}$
	Exiting from the Pistol	
x	The Horizontal Distance along the	т
	Thin Plate	
у	The Vertical Distance along the	т
	Thin Plate	
$\varepsilon_{\chi\chi}$	Normal Strain along the X-Axis	-
$\varepsilon_{yy}$	Normal Strain along the Y-Axis	-
$\gamma_{xy}$	Shear Strain	-
$\begin{bmatrix} \varepsilon_{\chi\chi} \end{bmatrix}$	Elastoplastic Strain Field near the	-
$\begin{bmatrix} \varepsilon_{yy} \\ \gamma_{xy} \end{bmatrix}_{ep}$	Crack Tip	
η	The Vertical Distance Where the	т
	Load Acts	
θ	The Variable Angular Position	deg
ν	Poisson's Ratio	-
ξ	The Horizontal Distance Where	т
	the Load Acts	
$\sigma_Y$	Yield Stress	Мра
$\sigma_{xx}$	Normal Stress along the X-Axis	Мра
$\sigma_{yy}$	Normal Stress along the Y-Axis	Мра
$ au_{xy}$	Shear Stress	Мра
$\begin{bmatrix} \sigma_{xx} \\ \sigma \end{bmatrix}$	Elastoplastic Stress Field near the	Мра
$\begin{bmatrix} \sigma_{yy} \\ \tau_{xy} \end{bmatrix}_{ep}$	Crack Tip	

### **1. Introduction:**

<sup>2</sup> Of a particular concern within the present work is to study the solid body, whose structure is experiencing large  ${}^{3}_{4}$  deformations and loss of contact between parts of the solid body itself, undergoing extreme loading which leads to the  ${}^{5}_{5}$  elastoplastic deformation with or without the occurrence of the total fracture. As a contributing fact, fracture may be  ${}^{6}_{5}$  evolved before, after, or in conjunction with the occurrence of the large deformation process [7].

<sup>8</sup> During the last few decades, a number of oil cargo ship failures have contributed to cascade oil into rich fishing <sup>9</sup>regions and coastal beach areas as well as the collision of the passenger liner *Titanic* with a large iceberg causing it to <sup>10</sup> to <sup>11</sup> experience brittle fracture with its parts and killing about 1500 passengers and crew members, as a consequence, all the <sup>12</sup> solid structures are to be susceptible to the same fate. Therefore, design analysts should be familiar with the fact that the <sup>13</sup> fracture phenomenon is regarded to be one of the most dangerous defects undergone by a solid body [16]. The stress <sup>14</sup> concentrations within fractured or collapsed structures, the existence of flaws, microcracks, or sharp notches, and the <sup>16</sup> fracture <sup>17</sup> phenomenon.

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To be investigated within the current research are crack-tip-nearby elastoplastic stress and strain fields, extents of 21 the yielded zone around the crack tip, and the crack-development speeds analytically and experimentally for simply-22 supported cracked thin plates, which have different aspect ratios (1, 1.334, and 2), crack lengths (10, 20, and 30 mm), and 23 plate alloy types (pure aluminum 1100 and aluminum-copper 2014 alloy types), under theoretically-assumed triangular-4 type impacting load [17].

The upcoming researches are elaborated so as to support the outlining subjects of the current research, which are to 28be cited within the dynamic crack propagation and fracture mechanics concepts, plastic strain and plastic-zone size 29evaluation procedures, impact loading of thin plates topics, and elastoplastic stress intensity factor formulations.

<sup>31</sup> M. Krawczuk, M. Palacz, and W. Ostachowicz (2004) **[10]** achieved their research in order to present the method <sup>32</sup> analysis of the wave propagation process in cracked plates. For modeling the plate new type of finite spectral plate <sup>34</sup>element with a crack was elaborated. It was assumed that the crack having an arbitrary length, depth and location was <sup>35</sup>parallel to one side of the plate. Elastic behavior of the plate at the crack location was considered as a line spring with a <sup>36</sup> aryvarying stiffness along the crack length.

G. G. Corbett, S. R. Reid, and W. Johnson (1996) [3] have reviewed recent research into the penetration and 40deformation of plates and cylinders by free-flying projectiles travelling at sub-ordnance velocities. It is shown that over <sup>41</sup>the last few years there has been a significant amount of experimental research into a wide range of projectile-target <sup>42</sup>configurations. Although most of this research has been concerned with the normal impact of monolithic metallic plates <sup>44</sup>tby non-deformable projectiles, valuable work has also been carried out on non-normal impact, impact by deformable <sup>45</sup>projectiles (including bullets of various guns which is used during the experiment), impact of non-homogeneous metallic <sup>46</sup>and non-metallic targets (including laminated targets) and impact of pipes and tubes.

<sup>48</sup> D. S. Dugdale (1960) [2] has investigated the yielding undergone at the end of a surface or through (internal) slit in  $_{50}$  a sheet by an external load, and obtained a relation between the extent of the plastic yielding and the external load  $_{51}$ applied. To verify this relation, panels containing internal and edge slits were loaded in tension and lengths of plastic  $_{52}$ zones were measured. The elastic stress intensity factors are normalized dynamically for ductile materials into  $_{54}$ elastoplastic stress intensity factors, in order to distinguish how much stresses and strains near the crack tip and speeds of  $_{55}$ the propagating cracks for an elastic-ideally plastic Tresca material which is experiencing an external load.

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<sup>57</sup> J. H. Underwood and D. P. Kendall (1969) [5] have utilized two independent experimental techniques so as to  $\frac{58}{59}$  measure the strain distribution within the plastically deformed region around a crack tip. By using a microscope, 60 permanent plastic deformations near the crack tip are investigated and it is compared with the method of Moiré grid

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interference which is used to measure the in-plane strain with the specimen grid engraved directly on the specimen  $^{1}$ surface. The testing arrangement allows measurement of at-load strain as well as residual strain. The measured strain  $^{2}$ distribution is compared with recent work by Swedlow using a finite-element numerical technique and with results of the  $^{3}_{4}$ etch-pit technique used by Hahn and Rosenfield.

### 62. Analytical Approach:

## 82.1 The Mathematical Model: Elastoplastic Stress and Strain Fields and Dugdale's Approach:

<sup>10</sup> The mathematical model of a cracked thin plate is shown in Fig. (1), the following underlying assumptions are 12adequately convenient to utilize in order to arrive at the final analytical expressions: the plate is thin enough for plane 13stress to occur, isothermal conditions are assumed for the linearly isotropic continuum, i.e., any temperature change  $^{14}$ during the impact process is of no concern within the present illustration, and the impacted-plate alloy type is  $^{16}$ homogenous and of a linearly-elastic-ideally-plastic behavior whose yield limit can be approximated, with fairly good 17results, by Tresca's failure criterion. Hence, proceeding from the plane-stress-based equilibrium equations for a solid  $^{18}$ medium, small-strain-theory-based kinematic constraints, and for-linearly-isotropic-alloy-type Hooke's law [7]



Fig. (1) The Centrally-Cracked-Plate Mathematical Model

56and also proceeding from the assumed-Airy's-stress-function relations

$$\int_{a}^{1} dx_{xx} = \frac{\partial^{2} \Omega}{\partial y^{2}}$$

$$\int_{a}^{2} \frac{\partial^{2} \Omega}{\partial x^{2}} \cdots \cdots \cdots (4)$$

$$\int_{5}^{5} \frac{\partial^{2} \Omega}{\partial x^{2}} \cdots \cdots \cdots (4)$$

$$\int_{5}^{5} \frac{\partial^{2} \Omega}{\partial x^{2}} = -\frac{\partial^{2} \Omega}{\partial x \partial y}$$

$$\int_{6}^{9} \text{we can arrive at the following bi-potential equation }$$

$$\int_{10}^{0} (\nabla^{2} \Omega) = 0 \cdots \cdots (5)$$

$$\int_{12}^{12} 1 \text{ Swhich can be solved by elaborating the complex-variable technique, the mean normal stress }$$

$$\int_{14}^{4} \frac{\partial^{2} \Omega}{\partial x^{2}} = \sigma_{xx} + \sigma_{yy} = \nabla^{2} \Omega \cdots \cdots (6)$$

$$\int_{16}^{7} \frac{\partial^{2} \Omega}{\partial x^{2}} = \sigma_{xx} + \sigma_{yy} = \nabla^{2} \Omega \cdots (7)$$

$$\int_{16}^{16} \frac{\partial^{2} \Omega}{\partial x^{2}} = \frac{1}{2} Re[x] (\Theta(z)) \cdots (7)$$

$$\int_{16}^{29} \frac{\partial^{2} \Omega}{\partial x^{2}} = \int_{10}^{10} \Theta(z) = \frac{1}{2} \frac{\partial^{2} \Omega}{\partial x^{2}} \cdots (8)$$

$$\int_{10}^{29} \frac{\partial^{2} \Omega}{\partial x^{2}} = \frac{1}{2} Re[x] (\Omega(z) + \Psi(z)] \cdots (9)$$

$$\int_{10}^{29} \frac{\partial^{2} \Omega}{\partial x^{2}} = \int_{10}^{10} \frac{\partial^{2} \Omega}{\partial x^{2}} = \int_{10}^{10} \frac{\partial^{2} \Omega}{\partial x^{2}} \cdots (9)$$

$$\int_{10}^{29} \frac{\partial^{2} \Omega}{\partial x^{2}} = \int_{10}^{10} \frac{\partial^{2} \Omega}{\partial x^{2}}$$

In order to arrive at the displacements, we must invoke the peculiarities of linearly-isotropic-material 44 <sup>45</sup>characteristics (Hooke's law) and the small-strain-theory-based kinematic constraints to (neglecting rigid-body terms  $^{46}_{47}$  emanated due to the translation and/or rotation of the rigid body) proceed into

of  $\Theta(z)$  produces another analytic function

54 Westergaard [4] has figured out a relation between the two analytic functions  $\Phi(z)$  and  $\Psi(z)$  by imposing the <sup>55</sup><sub>56</sub>boundary condition  $\tau_{xy} = 0$  along y = 0, for cracks experiencing tension tractions (mode I cracking), so as to proceed 57into 58

- ${}^{59}_{60}\overline{\Psi} = -z\overline{\Phi} \dots \dots \dots (12)$
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which may be substituted into eq. (10) and into eq. (11) in order to arrive at the following representation for predominant-<sup>1</sup>mode I stresses and displacements

By firstly solving for stresses and displacements in the vicinity of the crack tip (which lies at  $x = a_{cr}$ , y = 0) 16without any presence of traction stresses, and then imposing the traction stresses at  $|x| < a_{cr}$ , y = 0 in order to simulate 17the crack, Sedov [9] has pointed out a general solution for the analytic function  $\Phi(z)$  concerning an infinite plate whose 18 19crack is having a length of  $2a_{cr}$  (Fig. (1)), therefore, we have

$$\sum_{\substack{22\\23\\23\\24}}^{21} \overline{\Phi}_{I} = \frac{1}{\pi\sqrt{z^{2} - a_{cr}^{2}}} \int_{-a_{cr}}^{a_{cr}} \frac{\lambda_{2}(\xi)\sqrt{a_{cr}^{2} - \xi^{2}}}{z - \xi} d\xi \dots (15)$$

Introducing the expression for the elastic stress intensity factor

$$\sum_{\substack{29\\30}}^{27} \frac{1}{\sqrt{\pi a_{cr}}} \int_{-a_{cr}}^{a_{cr}} \lambda_2(\xi) \sqrt{\frac{a_{cr} + \xi}{a_{cr} - \xi}} d\xi \dots \dots (16)$$

<sup>31</sup><sub>32</sub>and studying the behavior of stresses and strains in the vicinity of the right-hand crack tip,  $(z + a_{cr} \approx 2a_{cr}, z - \xi \approx 33a_{cr} - \xi)$ , we obtain

The introduction of notation  $(z - a_{cr} = re^{i\theta})$  and the substitution of eq. (17) into eq.'s (13) and (14) will yield the <sup>40</sup>following local-elastic stress and displacement fields for mode I induced within a purely elastic material <sup>41</sup>

$$\begin{aligned} & \overset{42}{43} \sigma_{xx} \\ & \overset{43}{44} \sigma_{yy} \\ & \overset{46}{45} \sigma_{yy} \\ & \overset{46}{46} \sigma_{xy} \end{aligned} = \frac{K_I}{\sqrt{2\pi r}} \cos \frac{\theta}{2} \begin{bmatrix} 1 - \sin \frac{\theta}{2} \sin \frac{3\theta}{2} \\ 1 + \sin \frac{\theta}{2} \sin \frac{3\theta}{2} \\ \sin \frac{\theta}{2} \cos \frac{3\theta}{2} \end{bmatrix} \dots (18) \\ & \overset{49}{50} \begin{bmatrix} u_x \\ s_1 \\ u_y \end{bmatrix} = \frac{K_I}{2G} \sqrt{\frac{r}{2\pi}} \left( \frac{3 - \nu}{1 + \nu} - \cos \theta \right) \begin{bmatrix} \cos \frac{\theta}{2} \\ \sin \frac{\theta}{2} \end{bmatrix} \dots (19) \end{aligned}$$

<sup>54</sup> Within the present research elastoplastically-deformed aluminum alloys are to be dealt with, and the Dugdale-<sup>55</sup><sub>56</sub>assumed elastoplastic intensity factors must therefore be put into consideration instead of the elastic intensity factors. <sup>57</sup>Dugdale analytically proposed that by introducing the traction  $\sigma_{yy} = 0$  along  $|x| < a_{cr} + c$  and superimposing the <sup>58</sup>traction  $\sigma_{yy} = \sigma_Y$  along  $a_{cr} < |x| < a_{cr} + c$  (by utilizing the superposition principle) will yield the elastoplastic intensity <sup>59</sup><sub>60</sub>factor for Tresca-based linear elastic-ideally plastic materials and/or alloys [2]

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$$\frac{{}^{1}K_{I,ep}}{{}^{2}} = \sigma_{Y} \left[ \sqrt{\pi(a_{cr}+c)} - 2\sqrt{\frac{a_{cr}+c}{\pi}} \sin^{-1}\left(\frac{a_{cr}}{a_{cr}+c}\right) \right]$$

$$\frac{{}^{4}}{{}^{5}}_{{}^{6}} = \sigma_{Y} \left[ \sqrt{\pi\left(\frac{a_{o}}{2}+c\right)} - 2\sqrt{\frac{\frac{a_{o}}{2}+c}{\pi}} \sin^{-1}\left(\frac{\frac{a_{o}}{2}}{\frac{a_{o}}{2}+c}\right) \right] \dots (20)$$

<sup>10</sup>where  $\sigma_Y$  is the yield stress whose values must be determined by invoking the peculiarities of the plate theory, which is to <sup>11</sup>be discussed within the upcoming article, in conjunction with the Tresca's failure criterion. *c* is the plastic zone size, <sup>12</sup>awhich is emanated from the crack tip, whose values are to be determined by following what had been done by Dugdale 14[2] in order to arrive at 15

Now, it is meaningfully convenient to proceed into the following elastoplastic-crack-tip-nearby stress, 21displacement, and strain fields

$$\begin{aligned} & \overset{23}{2} \begin{bmatrix} \sigma_{xx} \\ 25 \\ 26 \\ \sigma_{yy} \\ 27 \\ 28 \\ 29 \\ \tau_{xy} \end{bmatrix}_{ep} \\ & = \frac{K_{I,ep}}{\sqrt{2\pi r}} \cos \frac{\theta}{2} \begin{bmatrix} 1 - \sin \frac{\theta}{2} \sin \frac{3\theta}{2} \\ 1 + \sin \frac{\theta}{2} \sin \frac{3\theta}{2} \\ \sin \frac{\theta}{2} \cos \frac{3\theta}{2} \\ \sin \frac{\theta}{2} \cos \frac{3\theta}{2} \end{bmatrix} \dots (22) \\ & \overset{33}{34} \begin{bmatrix} u_x \\ u_y \end{bmatrix}_{ep} \\ & = \frac{K_{I,ep}}{2G} \sqrt{\frac{r}{2\pi}} \left( \frac{3 - \nu}{1 + \nu} - \cos \theta \right) \begin{bmatrix} \cos \frac{\theta}{2} \\ \sin \frac{\theta}{2} \end{bmatrix} (23) \\ & \overset{35}{5} \begin{bmatrix} \varepsilon_{xx} \\ 37 \\ 38 \\ 39 \\ \varepsilon_{yy} \\ 40 \\ 41 \\ 42 \\ 43 \end{bmatrix}_{ep} \\ & = \begin{bmatrix} \frac{\Delta u_{x,ep}}{\Delta x} \\ \frac{\Delta u_{y,ep}}{\Delta y} \\ \frac{\Delta u_{x,ep}}{\Delta y} + \frac{\Delta u_{y,ep}}{\Delta x} \end{bmatrix} \dots \dots (24)$$

# 452.2 The Plate Theory and Tresca's Failure Criterion:

The general equation that governs the deflection of a simply-supported rectangular plate, which has a length b, <sup>48</sup>/<sub>49</sub> width a, and thickness h, is always represented by a double trigonometric series, therefore, we have **[18]** 

$$\sum_{\substack{52\\53\\54\\55}}^{50} w = \frac{-4F(t)}{\pi^4 a b D} \sum_{m=1}^{\infty} \sum_{n=1}^{\infty} \left[ \frac{\sin\left(\frac{m\pi\xi}{a}\right)\sin\left(\frac{n\pi\eta}{b}\right)}{\left(\frac{m^2}{a^2} + \frac{n^2}{b^2}\right)^2} \right] * \sin\left(\frac{m\pi x}{a}\right) \sin\left(\frac{n\pi y}{b}\right) \dots (25)$$

Since the bending moments about x and y axes depend upon the  $2^{nd}$  derivatives of the deflection equation with 57 sprespect to x and y as shown below

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$$\frac{1}{2} \begin{bmatrix} M_{x} \\ 2 \\ 3 \\ 4 \end{bmatrix} = \frac{4F(t)}{\pi^{4}ab} \sum_{m=1}^{\infty} \sum_{n=1}^{\infty} \left[ \frac{\left(\frac{m^{2}}{a^{2}} + \nu \frac{n^{2}}{b^{2}}\right)}{\left(\frac{n^{2}}{b^{2}} + \nu \frac{m^{2}}{a^{2}}\right)} \right] * \frac{\sin\left(\frac{m\pi\xi}{a}\right)\sin\left(\frac{m\pi\eta}{b}\right)\sin\left(\frac{m\pi\chi}{a}\right)\sin\left(\frac{n\pi\eta}{b}\right)}{\left(\frac{m^{2}}{a^{2}} + \frac{n^{2}}{b^{2}}\right)^{2}} \dots (26)$$

<sup>6</sup><sub>7</sub>where F(t) is the time-dependent impacting force which strikes the thin plate in a very short-time duration (by utilizing a 'spistol of a Glock-18 model whose bullet's specifications are given in table (1)) and it is engineered to deform the thin 9plate elastoplastically, further data for the aluminum-alloys specifications are illustrated in table (2). To acquire the full-<sup>1</sup><sup>0</sup>configuration-short-time-duration impacting load, it is adequately convenient to utilize the principles of work and energy  $^{11}_{12}$  (neglecting the air-resistance effects and temperature-change energy losses) and linear momentum principles as well as 13the triangular-type-impact-load assumption. We can therefore arrive at the short-time-duration impacting force [15] 

Since the bending moments can be proceeded into the in-plane elastic stresses [18]

$$21 \begin{bmatrix} \sigma_{xx} \\ \sigma_{yy} \\ 23 \\ 24 \\ \tau_{xy} \end{bmatrix} = \frac{1}{h^2} \begin{bmatrix} 6M_x \\ 6M_y \\ 3M_x \end{bmatrix} \dots \dots \dots \dots (28)$$

26 and consequently to the plane-stress-based elastic principal stress

$$\begin{bmatrix} \sigma_{x} + \sigma_{y} \\ \sigma_{1} \\ \sigma_{2} \\ \sigma_{3} \\ \sigma_{2} \\ \sigma_{3} \end{bmatrix} = \begin{bmatrix} \sigma_{x} + \sigma_{y} \\ \sigma_{x} + \sigma_{y} \\ \sigma_{x} + \sigma_{y} \\ \sigma_{x} + \sigma_{y} \\ \sigma_{x} - \sqrt{\left(\frac{\sigma_{x} - \sigma_{y}}{2}\right)^{2} + \left(\tau_{xy}\right)^{2}} \\ \sigma_{x} + \sigma_{y} \\ \sigma_{x} - \sigma_{y} \\ \sigma_{x$$

36in which  $\sigma_3 = 0$  for the plane-stress state, it is meaningful to finally arrive at the Dugdale-proposed predominant-yield-<sup>37</sup>stress value by using Tresca's criterion [19]

$${}^{39}_{40}\sigma_Y = \sigma_1 - \sigma_3 = \sigma_1 \dots \dots \dots (31)$$

42 Glock-18-Bullet Specifications [8][14]	
<sup>4</sup> <sup>3</sup> Muzzle velocity ( $v_1$ )	375 <sup>m</sup> / <sub>s</sub>
<sup>44</sup> <sub>45</sub> Bullet Mass $(m_o)$	0.00745 kg
46Bullet Type Used	9 * 19mm Parabellum
$\frac{4}{7}$ Rated Maximum Striking Pressure of a Bullet ( $P_o$ )	500 Mpa
Distance between the Pistol and the Thin Plate $(d)$	0.45 m
Contact Area between the Bullet and the Thin Plate $(A_o)$	$\frac{\pi}{-}*9^2 mm^2$
5 <u>1</u>	4
52 Table (1) Impacting-Bullets Spe	ecifications

Pure Aluminum 1100 Properties [11]	
<sup>1</sup> Poisson's Ratio ( $\nu$ )	0.334
<sup>2</sup> <sub>3</sub> Young's Modulus ( $E$ )	69 Gpa
4Shear Modulus (G)	26 Gpa
<sup>5</sup> Yield Limit ( <i>YS</i> )	8 Mpa
<sup>o</sup> <sub>7</sub> Specific Density ( $\rho$ )	$2720 \frac{kg}{2}$
8	$m^{-1}$
<sup>9</sup> Aluminum Copper 2014 Properties [6]	
11Poisson's Ratio (ν)	0.330
$\frac{12}{12}$ Young's Modulus (E)	72 Gpa
$1_4^3$ Yield Limit ( <i>YS</i> )	11 Mpa
15Specific Density ( $\rho$ )	$2800 \frac{kg}{2}$
Ц6 17	/m <sup>3</sup>

Table (2)	Aluminum	Alloys S	pecifications
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### 20**2.3 Crack Development: Criteria and Analyses:** 21

The Griffith crack criterion states: a crack grows to a further size if the energy required to from an additional crack  ${}^{23}_{24}da_{cr}$  can just be delivered by a system. It has been demonstrated that at the onset of fracture instability the energy release  ${}^{25}_{26}$  rate (which is equal to  $\frac{K_I^2}{E}$  for the plane-stress-based-opening-mode cracking [1]) given by  ${}^{27}_{28}G_r = \frac{d}{E}(E - U)$  (32)

$$\sum_{29}^{28} G_I = \frac{u}{da_{cr}} (F_e - U_e) \dots \dots \dots (32)$$

<sup>31</sup>where  $F_e$  is the external-load work and  $U_e$  is the plate elastic energy, is equal to the crack resistance (which equals the <sup>32</sup>/<sub>32</sub> scritical energy release rate  $G_{Ic} = \frac{\pi a_c \sigma_{\infty}^2}{E}$  at the fracture-instability onset) given by

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<sup>39</sup>where  $W_{cr}$  is the crack-formation energy. A total analysis should therefore lead to the fact that the energy release rate is <sup>40</sup>the same as the critical one at the onset of instability, therefore, we obtain <sup>41</sup>

 $^{46}_{47}$  for purely elastic materials like glass, for elastoplastically-deformed alloys we utilize

The crack-size critical value  $a_c$  is regarded as the illustrating value of whether or not the crack is propagating, and a 54 hypothesis should therefore be kept in consideration in order to recognize the crack-development state

- The crack cannot grow to any further size when the existing crack size within the impacted plate is less than the critical-crack-size value, i.e.,  $a_{cr} < a_c$ .
- The crack will propagate and immediately stop only when the existing crack size is just approaching the criticalcrack-size value, i.e.,  $a_{cr} \approx a_c$ .
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• Dynamic crack propagation will occur and the crack will grow continuously when the impacted-plate-existed crack size is larger than the critical crack size, i.e.,  $a_{cr} > a_c$ , moreover, the kinetic-energy-based crack propagation speed (suggested by Mott [12]) is therefore given by

$$\int_{7}^{4} \frac{1}{6a_{cr}} \approx 0.38 \sqrt{\frac{E}{\rho}} \left(1 - \frac{a_c}{a_{cr}}\right) \approx 0.38 \sqrt{\frac{E}{\rho}} \left(1 - \frac{2a_c}{a_o}\right) \dots \dots (36)$$

<sup>9</sup>3. Experimental Technique:

## <sup>1</sup><sub>12</sub>3.1 Cracks-and-Grids-Implementation Process:

<sup>13</sup> <sup>14</sup> Once the initially-existed-flaws testing, surface-finish testing, and chemical-composition testing for the 6mm-<sup>15</sup>thickness-aluminum-alloy specimens, whose specifications are illustrated in table (3), are accomplished (Fig. (2) to Fig. <sup>16</sup>(4)), grids and cracks are engraved within the aluminum-alloy-based plates surface using a computer-controlled CNC <sup>17</sup><sub>18</sub>machine (Fig. (5)) **[20]**. Table (4) is underlining the specifications for the implemented cracks and grids within the surface <sup>19</sup>90f pure aluminum 1100 and aluminum copper 2014 plates.

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<sup>2</sup> <sup>1</sup> Type	No.	Dimensions	Aspect Ratio	Crack Length
<sup>2</sup> <sup>2</sup> Pure Aluminum 1100	3	21*21cm	1.0000	1cm, 2cm, and 3cm
<sup>2</sup> <sup>4</sup> Pure Aluminum 1100	3	21*16cm	1.3334	1cm, 2cm, and 3cm
<sup>2</sup> 5Pure Aluminum 1100	3	21*11cm	2.0000	1cm, 2cm, and 3cm
Aluminum-Copper 2014	3	21*21cm	1.0000	1cm, 2cm, and 3cm
28Aluminum-Copper 2014	3	21*16cm	1.3334	1cm, 2cm, and 3cm
<sup>2</sup> 9Aluminum-Copper 2014	3	21*11cm	2.0000	1cm, 2cm, and 3cm
30		Table (3) Alumi	num-Alloy Plates Spe	ecifications



<sup>43</sup> Fig. (2) The Initially-Existed-Flaws X-ray Testing for the
Aluminum-Alloy Plates. All Plates are Exhibiting Good
Surface Properties



Fig. (3) Aluminum-Alloy Plates Surface-Finish Testing

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 15 Fig. (4) Plates Chemical-Composition Testing. The Left and the Right Pictures Exhibit the Element-Concentrations List
 16 for Pure Aluminum 1100 and Aluminum Copper 2014 Specimens, Respectively.



Fig. (5) The Crack-and-Grid-Implementing Computer-Controlled CNC Machine.

Grid Specifications		
Dimensions	20 <i>mm</i> * 20 <i>mm</i>	
Spacing Between Each Grid Line	1 <i>mm</i>	
Depth of the Grid Line	0.001 <i>mm</i>	
Width of the Grid Line0.1mm		
Crack Specifications		
Crack Type	Surface Crack	
Crack Position	Centered Crack	
Crack Depth	2 <i>mm</i>	

Table (4) The-Engraved-Cracks-and-Grids Specifications.

#### <sup>49</sup> 50**3.2 The-Impact-Testing Unit:**

The test unit shown in Fig. (6) is to be executing the impact test for all the aluminum-alloy plates [3]. To hold the <sup>53</sup>whole testing unit in place, connecting bolts engraved into the ground are fixing the test rig without being displaced nor <sup>54</sup>cotated in any direction during the-impact-test occurrence. Supports on which the specimens are to be mounted are found <sup>56</sup>so within the internal frame of the test unit, these three supports are dimensioned in such a way that all the plate are, with an <sup>57</sup>accurate way of establishing the plates onto the corresponding supports and these plates are then connected with the <sup>58</sup>internal frame by 6mm-diameter connecting bolts, mounted onto their corresponding supports (Fig. (7)). The test-unit <sup>60</sup>external frame contains a rectangular thick plate, made from wood and used to fit perfectly with the external frame (Fig.

(6)), which is having three holes through which the bullets, launched by a Glock-18-type sidearm, are striking the thin  $^{1}$ plates mounted on the within-the-internal-frame supports. These holes are engineered so that, since the pistol's end is to  $^{2}$ coincide perfectly with the designed hole, the pistol is accurately directed towards the grid-nearby-right-hand-crack-tip  $^{4}$ where the crack is expected to traverse through the continuum considered. Finally, the four faces forming the surface area 50f the test unit are covered by steel sheets, riveted altogether with the test-unit external structure, in order to avoid any finconvenient hazards which may be resulted from the-striking-bullets rebound or from the launched-bullets harmful  $^{7}_{8}$ temperature.



Fig. (6) The-Impact-Testing Unit



Fig. (7)The-Test-Unit Dimensions Needed to Execute the Impact Process

# 303.3 Aluminum-Plates Microstructure-Testing Unit:

In order to arrive at the permanently-induced displacements, plastic-zone extents, and dynamically-propagating-34 cracks speeds, a computer-controlled microscope is processed to arrive at the experimental output data before and after 35the impact-process occurrence [5]. As shown in Fig. (8), the computer-controlled microstructure-testing unit is elaborated <sup>36</sup>so as to proceed into the grid configuration before and after the-impact-test achievement. The experimental technique can <sup>37</sup><sub>38</sub>therefore be summarized into the following overall procedure in Fig. (9) shown below. 



Fig. (8) The-Computer-Controlled Microstructure-Testing Unit



Fig. (9) The Experimental-Technique Procedure

### 4. Results and Discussion:

### 24.1 Plastic-Zone Size:

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<sup>4</sup> Referring to Fig (10), it is found that the plastic-zone extent increases as the crack length increases, and it is also found that the more the plate aspect ratio is, the less the plastic-zone extent will be. A further illustration must therefore 7lead to the fact that the pure aluminum1100 plates are exhibiting more yielded-zone extents than what is exhibited by the <sup>8</sup>aluminum copper 2014 ones.



<sup>26</sup>Fig. (10) The Plastic-Zone Size. The Left and The Right Charts are for Pure Aluminum 1100 and Aluminum Copper 2014
 Plates Respectively.

#### 29 30**4.2 Crack-Development Speed:**

It has been previously shown that the critical crack length is the decisive value to illustrate whether or not the crack <sup>3</sup>A<sub>3</sub> is propagating, it is demonstrated theoretically and experimentally that the crack will dynamically propagate through a <sup>3</sup>A<sub>3</sub> certain path within the aluminum-alloy plates. Fig (11) is indicating that the crack-development speed decreases as the <sup>3</sup>Cerack length increases [10], and also is implying that the high-aspect-ratio plates experience higher propagating-cracks <sup>3</sup>Speeds than the low-aspect-ratio plates. Moreover, the pure aluminum 1100 plates are exhibiting less propagating-cracks-<sup>38</sup>Speeds than the aluminum copper 2014 ones.



Fig. (11) The Crack-Development Speed. The Left and The Right Charts are for Pure Aluminum 1100 and Aluminum Copper 2014 Plates Respectively.

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### 4.3 Crack-Tip-nearby-Stress Field:

It is demonstrated, referring to Fig. (12) for 10-mm-crack-length and 1-aspect-ratio pure aluminum 1100 plate, that the more the distance of the gridpoint from the crack tip is, the less the stresses within that gridpoint will be. The selastoplastic stresses attain their maximum values at the instant when the impacting bullet is just striking the thin plate, 6.e. t = 0.



Fig. (12) Crack-Tip-nearby Elastoplastic Stress Field

# **434.4 Experimental Crack-Tip-nearby-Strain Field:**

It is concluded experimentally, with the aid of Fig. (13), that the crack-tip-nearby-strain field values are increasing to the distance between the gridpoints and the crack tip decreases, until these strain values attain their maximum values at tasthe point where the crack tip lies at. The upcoming charts, found within Fig. (13), are elaborated to establish the straintage of the point where the crack tip lies at. The upcoming charts, found within Fig. (13), are elaborated to establish the straintage of the point where the crack tip lies at. The upcoming charts, found within Fig. (13), are elaborated to establish the straintage of the point where the crack tip lies at. The upcoming charts found aspect ratio are 10mm and 1, respectively.



# <sup>49</sup>5. Concluding Remarks:

The Discussed analytical and experimental results demonstrate the fact that whichever increase is encountered to 53the yielded-zone-size values, which is resulted from the long-cracks utilization or plate-aspect-ratio reduction, etc., leads <sup>54</sup>to some decrease in the crack-development-speed values for an elastoplastically-deformed cracked plate, and vice versa.  $^{55}_{56}$ Furthermore, a total analysis should therefore proceed into the establishment of the crack-tip-nearby elastoplastic stress <sup>5</sup><sup>7</sup>and strain fields' behavior, and also lead to the required satisfactory-design environment thereafter.

# Acknowledgments:

Special thanks are given to my father Abdul-Hussein Ali Owayez, to my mother Hussniyah Alwan Maseer, and to
 <sup>3</sup>my co-author Fathy Abdul-Sahib Al-Shamma for their unending and valuable efforts.

#### <sup>5</sup> 6<u>Appendices:</u>

#### **Appendix (1): The Analytical-Technique-Based-Flow-Chart:**



Fig. (A1) The Analytical-Solution-Based Flow Chart



Fig. (A2) The Analytical-Solution-Based Flow Chart (Continued)



Fig. (A3) The Analytical-Solution-Based Flow Chart (Continued)

#### Appendix (2): The-Experimental-Output Data:

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The Experimental output data, for a pure aluminum 1100 plate whose crack length and aspect ratio are 10mm and  $^{3}_{4}$ 1, respectively, are illustrated in the following table

X(mm)	Y(mm)	U <sub>x</sub> (µm)	U <sub>y</sub> (µm)
0	0	0	0
4	0	264	0
8	0	373	0
12	0	457	0
16	0	528	0
20	0	590	0
0	2	264	267
4	2	300	71
8	2	387	48
12	2	465	38
16	2	533	33
20	2	594	30
0	4	373	378
4	4	375	157
8	4	425	101
12	4	487	80
16	4	548	68
20	4	605	60
0	6	458	463
4	6	452	245
8	6	475	160
12	6	520	124
16	6	571	104
20	6	622	92
0	8	528	535
4	8	522	326
8	8	530	222
12	8	560	171
16	8	601	143
20	8	645	125
0	10	591	598
4	10	585	400
8	10	586	285
12	10	604	221
16	10	635	184
20	10	672	160
Plastic Z	one Size	2.50n	ım
Crack E	xtension	11m	m

<sup>57</sup><sub>58</sub>Table (A1) The Experimental Output Data for 10mm-Crack-Length and 1-Aspect-Ratio Pure Aluminum 1100 Thin Plate

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Fig. (1) The Centrally-Cracked-Plate Mathematical Model



Fig. (2) The Initially-Existed-Flaws X-ray Testing for the Aluminum-Alloy Plates. All Plates are Exhibiting Good Surface Properties



Fig. (3) Aluminum-Alloy Plates Surface-Finish Testing



Fig. (4) Plates Chemical-Composition Testing. The Left and the Right Pictures Exhibit the Element-Concentrations List for Pure Aluminum 1100 and Aluminum Copper 2014 Specimens, Respectively.



Fig. (5) The Crack-and-Grid-Implementing Computer-Controlled CNC Machine.



Fig. (6) The-Impact-Testing Unit



Fig. (7)The-Test-Unit Dimensions Needed to Execute the Impact Process



Fig. (8) The-Computer-Controlled Microstructure-Testing Unit



Fig. (9) The Experimental-Technique Procedure



Fig. (10) The Plastic-Zone Size. The Left and The Right Charts are for Pure Aluminum 1100 and Aluminum Copper 2014 Plates Respectively.



Fig. (11) The Crack-Development Speed. The Left and The Right Charts are for Pure Aluminum 1100 and Aluminum Copper 2014 Plates Respectively.



Fig. (12) Crack-Tip-nearby Elastoplastic Stress Field





Fig. (13) Crack-Tip-nearby Strain Field.



Fig. (A1) The Analytical-Solution-Based Flow Chart



Fig. (A2) The Analytical-Solution-Based Flow Chart (Continued)



Fig. (A3) The Analytical-Solution-Based Flow Chart (Continued)

Glock-18-Bullet Specifications [8][14]	
Muzzle velocity $(v_1)$	375 m/s
Bullet $Mass(m_o)$	0.00745 kg
Bullet Type Used	9 * 19mm Parabellum
Rated Maximum Striking Pressure of a Bullet $(P_o)$	500 Mpa
Distance between the Pistol and the Thin Plate $(d)$	0.45 m
Contact Area between the Bullet and the Thin Plate $(A_o)$	$\frac{\pi}{4} * 9^2 mm^2$

Table (1) Impacting-Bullets Specifications

Pure Aluminum 1100 Properties [11]	
Poisson's Ratio $(v)$	0.334
Young's Modulus (E)	69 Gpa
Shear Modulus (G)	26 Gpa
Yield Limit (YS)	8 <i>Mpa</i>
Specific Density ( $\rho$ )	2720 $kg/m^3$
Aluminum Copper 2014 Properties [6]	
Poisson's Ratio $(v)$	0.330
Young's Modulus (E)	72 Gpa
Yield Limit (YS)	11 Mpa
Specific Density ( $\rho$ )	$2800 \frac{kg}{m^3}$

Table (2) Aluminum-Alloys Specifications

Туре	No.	Dimensions	Aspect Ratio	Crack Length
Pure Aluminum 1100	3	21*21cm	1.0000	1cm, 2cm, and 3cm
Pure Aluminum 1100	3	21*16cm	1.3334	1cm, 2cm, and 3cm
Pure Aluminum 1100	3	21*11cm	2.0000	1cm, 2cm, and 3cm
Aluminum-Copper 2014	3	21*21cm	1.0000	1cm, 2cm, and 3cm
Aluminum-Copper 2014	3	21*16cm	1.3334	1cm, 2cm, and 3cm
Aluminum-Copper 2014	3	21*11cm	2.0000	1cm, 2cm, and 3cm

Table (3) Aluminum-Alloy Plates Specifications

Grid Specifications				
Dimensions	20mm * 20mm			
Spacing Between Each Grid Line	1mm			
Depth of the Grid Line	0.001mm			
Width of the Grid Line	0.1mm			
Crack Specifications				
Crack Type	Surface Crack			
Crack Position	Centered Crack			
Crack Depth	2mm			

Table (4) The-Engraved-Cracks-and-Grids Specifications.

X(mm)	Y(mm)	U <sub>x</sub> (µm)	U <sub>y</sub> (µm)	
0	0	0	0	
4	0	264	0	
8	0	373	0	
12	0	457	0	
16	0	528	0	
20	0	590	0	
0	2	264	267	
4	2	300	71	
8	2	387	48	
12	2	465	38	
16	2	533	33	
20	2	594	30	
0	4	373	378	
4	4	375	157	
8	4	425	101	
12	4	487	80	
16	4	548	68	
20	4	605	60	
0	6	458	463	
4	6	452	245	
8	6	475	160	
12	6	520	124	
16	6	571	104	
20	6	622	92	
0	8	528	535	
4	8	522	326	
8	8	530	222	
12	8	560	171	
16	8	601	143	
20	8	645	125	
0	10	591	598	
4	10	585	400	
8	10	586	285	
12	10	604	221	
16	10	635	184	
20	10	672	160	
Plastic Z	Cone Size	2.50	mm	
Crack Extension		11mm		

 Table (A1) The Experimental Output Data for 10mm-Crack-Length and 1-Aspect-Ratio Pure Aluminum 1100 Thin Plate